Fault-Tolerant Distributed Transactions on Blockchain Toward Scalable Blockchain



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Scalability versus Fully-Replicated Blockchains

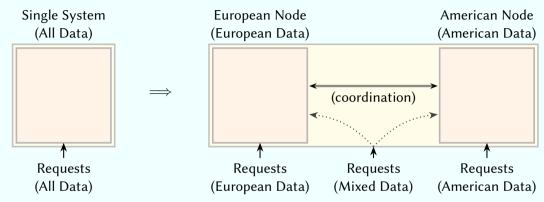
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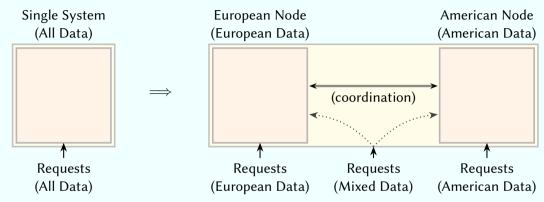
Full replication: adding resources (replicas) \implies less performance!

Distributed Systems: Scalability



Partition the system: More storage and *potentially* more performance. Potentially *lower latencies* if data ends up closer to users.

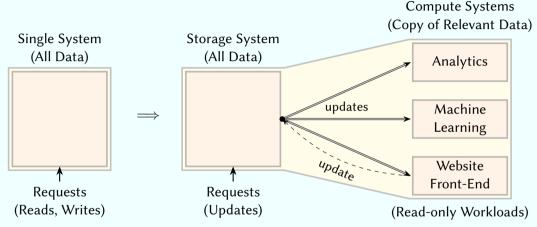
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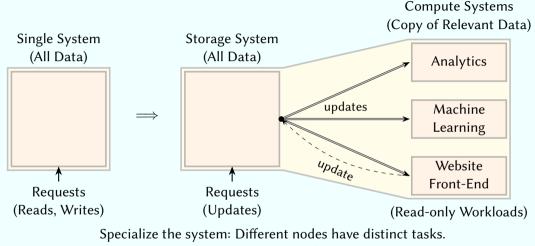
Adding shards \implies adding throughput (parallel processing), adding storage.

Distributed Systems: Specialization



Specialize the system: Different nodes have distinct tasks. Specialized hardware and software *per* task.

Distributed Systems: Specialization



Specialized hardware and software per task.

Specializing roles \implies adding throughput (parallel processing, specialized hardware, ...).

Central Ideas for Improvement

Reminder

We can make a resilient system that manages data: e.g., fully-replicated blockchains.

Role Specialization: make the storage system a blockchain. Requires: reliable read-only updates of the blockchain. Permissionless blockchains: light clients!

 Sharding: make each shard an independent blockchain. Requires: *reliable communication between blockchains*. Permissionless blockchains: relays, atomic swaps!

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 Sharding: make each shard an independent blockchain. Requires: *reliable communication between blockchains*. Permissionless blockchains: relays, atomic swaps!

Consensus is of no use here if we want efficiency.

Reliable Read-Only Updates of Fault-Tolerant Clusters

Definition

Let ${\mathcal C}$ be a cluster deciding on a sequence of transactions ${\mathcal L}$ and ${\tt L}$ be a learner.

The *Byzantine learning problem* is the problem of sending \mathcal{L} from \mathcal{C} to L such that:

- ▶ the learner L will eventually *receive all* decided transactions;
- ► the learner L will *only receive* decided transactions.

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Practical requirements

- Minimizing overall communication.
- Load balancing among all replicas in C.

Background: Information Dispersal Algorithms

Definition

Let *v* be a value with storage size s = ||v||. An *information dispersal algorithm* can encode *v* in **n** pieces *v'* such that *v* can be *decoded* from every set of **n** – **f** such pieces.

Theorem (Rabin 1989)

The IDA algorithm is an optimal information dispersal algorithm:

- Each piece v' has size $\left\lceil \frac{\|v\|}{\mathbf{n}-\mathbf{f}} \right\rceil$.
- The **n f** pieces necessary for decoding have a total size of $(n f) \left[\frac{\|v\|}{(n-f)} \right] \approx \|v\|$.

Idea: C sends a ledger to learner L

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- 4. L receives at least $\mathbf{n} \mathbf{f}$ distinct pieces and decodes S.

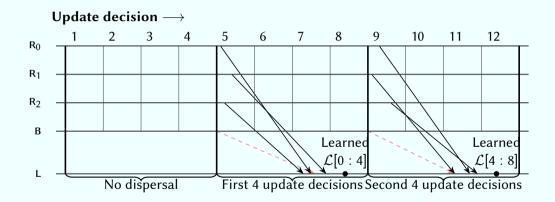
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Observation ($\mathbf{n} > 2\mathbf{f}$)

- Replica R_i sends at most $B = \left\lceil \frac{\|S\|}{n-f} \right\rceil + c \le \frac{2\|S\|}{n} + 1 + c = \mathcal{O}(\frac{\|S\|}{n} + c)$ bytes.
- Learner L receives at most $\mathbf{n} \cdot B = \mathcal{O}(||S|| + c\mathbf{n})$ bytes.

Communication by the Delayed-Replication Algorithm

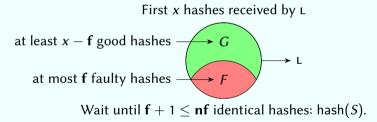


► Use checksums hash(*S*).

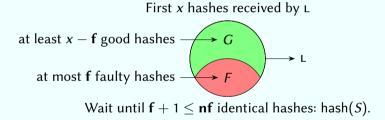
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- At least $\mathbf{n} \mathbf{f} > \mathbf{f}$ messages with correct *checksums*.



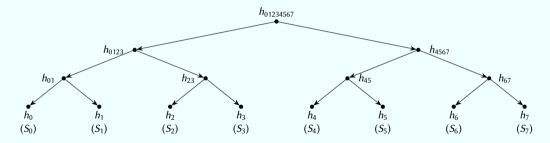
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Intensive for learners: one can choose n – f out of n messages in (ⁿ_{n-f}) ways only one such choice is guaranteed to be correct!

Decoding S Using Tree Checksums

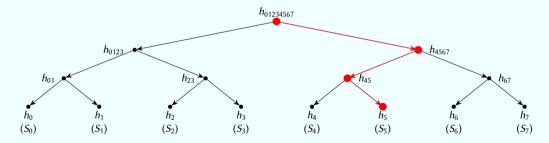
Use Merkle-trees to construct checksums Consider 8 replicas and a sequence S. We construct the checksum $C_5(S)$ of S (used by R_5).



Construct a Merkle tree for pieces S_0, \ldots, S_7 .

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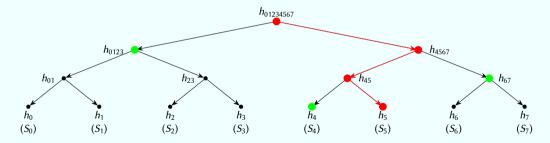
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Determine the path from root to S_5 .

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Select root and neighbors: $C_5(S) = [h_4, h_{67}, h_{0123}, h_{01234567}].$

Delayed-Replication: Main Result (n > 2f)

Theorem

Consider the learner L, replica R, and decided transactions \mathcal{T} . The delayed-replication algorithm with tree checksums guarantees

- 1. \sqcup will learn \mathcal{T} ;
- 2. L will receive at most $|\mathcal{T}|$ messages with a total size of $\mathcal{O}(||\mathcal{T}|| + |\mathcal{T}|\log n)$;
- 3. L will only need at most $\frac{|\mathcal{T}|}{n}$ decode steps;
- 4. R will sent at most $\frac{|\mathcal{T}|}{n}$ messages to L of size $\mathcal{O}(\frac{||\mathcal{T}|| + |\mathcal{T}| \log n}{n})$.

Application: Scalable Storage for Resilient Systems

- Replicas typically only need the *current data V* to decide on future updates.
- Replicas only need the full ledger \mathcal{L} for *recovery*.
- We can use *delayed-replication* to reduce the data each replica has to store.

Theorem

The storage cost per replica can be reduced from

$$\mathcal{O}(\|\mathcal{L}\| + \|V\|)$$
 to $\mathcal{O}(\frac{\|\mathcal{L}\|}{\mathbf{n} - \mathbf{f}} + \frac{|\mathcal{L}|}{\mathbf{n}}\log(\mathbf{n}) + \|V\|).$

Reliable Communication between Fault-Tolerant Clusters

Definition

Let C_1, C_2 be two clusters, both having non-faulty replicas.

The *cluster-sending problem* is the problem of sending a value v from C_1 to C_2 such that:

- 1. non-faulty replicas in C_2 receive v;
- 2. non-faulty replicas in C_1 confirm that v was received by the non-faulty replicas in C_2 ;
- 3. replicas in C_2 only receive v if all non-faulty replicas in C_1 agree upon sending v.

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Informal Definition

Successfully sending a value v from a cluster C_1 to a C_2 without any faulty replicas being able to *disrupt sending* or send *alternative forged values*.

Goal: send a value *v* from cluster C_1 to cluster C_2 .

Assumptions

- Every replica in C_1 has a *certificate* cert (v, C_1) that proves agreement.
- Communication is *reliable*.
- At-most *two* replicas faulty in each cluster.

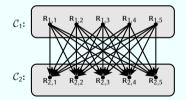
$$\mathcal{C}_{1}: \begin{bmatrix} \mathsf{R}_{1,1} & \mathsf{R}_{1,2} & \mathsf{R}_{1,3} & \mathsf{R}_{1,4} & \mathsf{R}_{1,5} \end{bmatrix}$$

$$C_2$$
: $R_{2,1}^{\bullet}$ $R_{2,2}^{\bullet}$ $R_{2,3}^{\bullet}$ $R_{2,4}^{\bullet}$ $R_{2,5}^{\bullet}$

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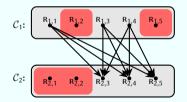


Broadcast: every replica in C_1 sends pairs $(v, cert(v, C_1))$ to every replica in C_2 .

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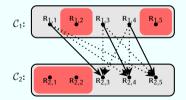


Faulty replicas can *fail* to send (in C_1) or to receive (in C_2).

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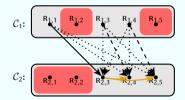


Non-faulty replicas in C_2 only need at-least one message $(v, cert(v, C_1))$.

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Replicas in C_2 can redistribute $(v, cert(v, C_1))$.

Basic Cluster-Sending via Broadcasting

Goal: send a value *v* from cluster C_1 to cluster C_2 .

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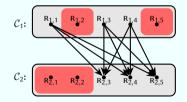
$$C_{1}: \begin{array}{c|c} R_{1,1} & R_{1,2} & R_{1,3} & R_{1,4} & R_{1,5} \\ \hline \\ C_{2}: & R_{2,1}^{\bullet} & R_{2,2}^{\bullet} & R_{2,3}^{\bullet} & R_{2,4}^{\bullet} & R_{2,5}^{\bullet} \end{array}$$

With certificates: a single message between non-faulty sender and receiver is sufficient!

Goal: send a value *v* from cluster C_1 to cluster C_2 .

Assumptions

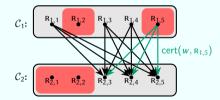
- Every replica $R \in C_1$ can only *claim* agreement via a digital signature cert(v, R).
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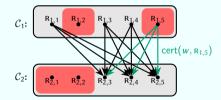


Faulty replicas can *lie* and send cert(w, R) without agreement on w.

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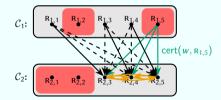


Claims from *three* distinct replicas in C_1 : at-least one from a non-faulty replica.

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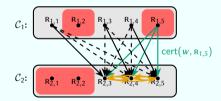


Replicas in C_2 can redistribute (v, cert(v, R)).

Goal: send a value *v* from cluster C_1 to cluster C_2 .

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- Communication is *reliable*.
- At-most *two* replicas faulty in each cluster.



Without certificates: *at least* \mathbf{f}_{C_1} + 1 distinct received messages by non-faulty senders!

Efficient Cluster-Sending

Cluster-Sending via broadcasting: straightforward, not efficient:

- ▶ With certificates: $(\mathbf{f}_{C_1} + 1)(\mathbf{f}_{C_2} + 1) \approx \mathbf{f}_{C_1} \times \mathbf{f}_{C_2}$ messages.
- ▶ With claims: $(2\mathbf{f}_{C_1} + 1)(\mathbf{f}_{C_2} + 1) \approx 2\mathbf{f}_{C_1} \times \mathbf{f}_{C_2}$ messages.

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Local communication versus global communication

	Ping round-trip times (ms)						<i>Bandwidth (</i> Mbit/s)					
	OR	IA	Mont.	BE	ΤW	Syd.	OR	IA	Mont.	BE	ΤW	Syd.
Oregon	≤ 1	38	65	136	118	161	7998	669	371	194	188	136
lowa		≤ 1	33	98	153	172		10004	752	243	144	120
Montreal			≤ 1	82	186	202			7977	283	111	102
Belgium				≤ 1	252	270				9728	79	66
Taiwan					≤ 1	137					7998	160
Sydney						≤ 1						7977

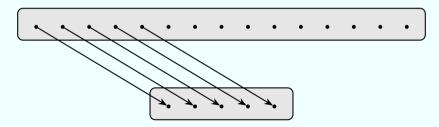
Goal: Minimize communication between clusters.

Proposition (assuming certificates)

Any correct algorithm needs to send at least 14 messages.

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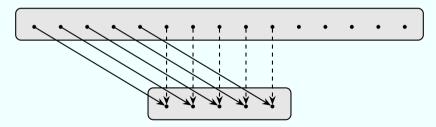
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Minimize impact of faulty replicas: minimum number of messages per participant.

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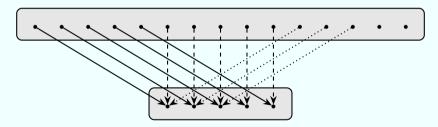
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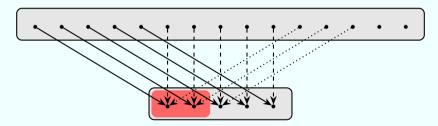
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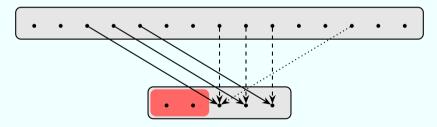
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Any $\mathbf{f}_{\mathcal{C}_2}$ replicas in \mathcal{C}_2 can be faulty: top $\mathbf{f}_{\mathcal{C}_2}$ receivers receive at-least 6 messages.

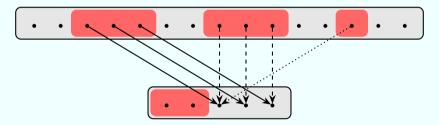
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Only $f_{\mathcal{C}_1}$ messages remaining, can all be sent by faulty replicas in \mathcal{C}_1 .

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Basic Idea

- One message needs to be exchanged between a non-faulty sender and receiver.
- Have to deal with size imbalances between clusters.

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Have to deal with size imbalances between clusters.

Theorem Let C_1, C_2 be two clusters and let $\{i, j\} = \{1, 2\}$ such that $\mathbf{n}_{C_i} \ge \mathbf{n}_{C_i}$. Let

$$q_i = (\mathbf{f}_{C_i} + 1) \operatorname{div} \mathbf{n} \mathbf{f}_{C_j},$$

$$r_i = (\mathbf{f}_{C_i} + 1) \operatorname{mod} \mathbf{n} \mathbf{f}_{C_j},$$

$$\sigma_i = q_i \mathbf{n}_{C_j} + r_i + \mathbf{f}_{C_j} \operatorname{sgn} r_i$$

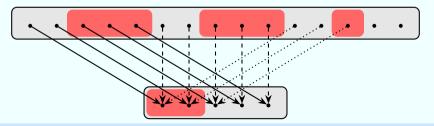
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Let C_1, C_2 be two clusters and let

$$q_{1} = (\mathbf{f}_{C_{1}} + 1) \operatorname{div} \mathbf{n} \mathbf{f}_{C_{2}} = 7 \operatorname{div} 3 = 2,$$

$$r_{1} = (\mathbf{f}_{C_{1}} + 1) \operatorname{mod} \mathbf{n} \mathbf{f}_{C_{2}} = 7 \operatorname{mod} 3 = 1,$$

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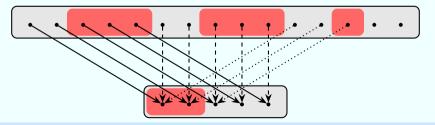
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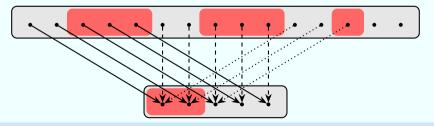
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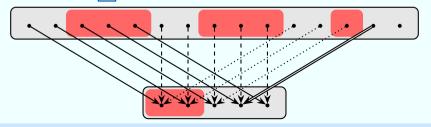
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Lower-Bound for Cluster-Sending with Claims

Basic Idea

- $f_{C_1} + 1$ message needs to be sent by distinct non-faulty senders to non-faulty receiver.
- Have to deal with size imbalances between clusters.

Theorem

Let C_1, C_2 be two clusters and let $\{i, j\} = \{1, 2\}$ such that $\mathbf{n}_{C_i} \ge \mathbf{n}_{C_j}$. Let

$q_1=(2\mathbf{f}_{\mathcal{C}_1}+1)\operatorname{div}\mathbf{nf}_{\mathcal{C}_2},$	$q_2 = (\mathbf{f}_{\mathcal{C}_2} + 1) \operatorname{div} (\mathbf{n} \mathbf{f}_{\mathcal{C}_1} - \mathbf{f}_{\mathcal{C}_1})$
$r_1 = (2\mathbf{f}_{\mathcal{C}_1} + 1) \operatorname{mod} \mathbf{n} \mathbf{f}_{\mathcal{C}_2},$	$r_2 = (\mathbf{f}_{\mathcal{C}_2} + 1) \operatorname{mod} (\mathbf{n} \mathbf{f}_{\mathcal{C}_1} - \mathbf{f}_{\mathcal{C}_1})$
$ au_1 = q_1 \mathbf{n}_{\mathcal{C}_2} + r_1 + \mathbf{f}_{\mathcal{C}_2} \operatorname{sgn} r_1$	$ au_2 = q_2 \mathbf{n}_{\mathcal{C}_1} + r_2 + 2 \mathbf{f}_{\mathcal{C}_1} \operatorname{sgn} r_2.$

Bijective Sending with Certificates

Assume $\mathbf{f}_{\mathcal{C}_1} + \mathbf{f}_{\mathcal{C}_2} + 1 \leq \min(\mathbf{n}_{\mathcal{C}_1}, \mathbf{n}_{\mathcal{C}_2}).$

We have $\sigma_1 = \sigma_2 = \mathbf{f}_{\mathcal{C}_1} + \mathbf{f}_{\mathcal{C}_2} + 1$.

Protocol for the sending cluster C_1 :

1: All replicas in $\mathcal{G}_{\mathcal{C}_1}$ agree on *v* and construct cert(*v*, \mathcal{C}_1).

- 2: Choose replicas $S_1 \subseteq C_1$ and $S_2 \subseteq C_2$ with $\mathbf{n}_{S_2} = \mathbf{n}_{S_1} = \mathbf{f}_{C_1} + \mathbf{f}_{C_2} + 1$.
- 3: Choose a bijection $b: S_1 \rightarrow S_2$.
- 4: for $\mathbf{R}_1 \in S_1$ do
- 5: R_1 sends $(v, cert(v, C_1))$ to $b(R_1)$.

Protocol for the receiving cluster C_2 :

6: event $R_2 \in \mathcal{G}_{\mathcal{C}_2}$ receives $(w, \operatorname{cert}(w, \mathcal{C}_1))$ from $R_1 \in \mathcal{C}_1$ do

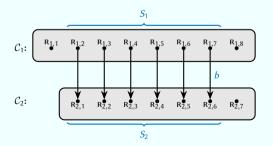
- 7: Broadcast $(w, cert(w, C_1))$ to all replicas in C_2 .
- 8: event $R'_2 \in \mathcal{G}_{\mathcal{C}_2}$ receives $(w, cert(w, \mathcal{C}_1))$ from $R_2 \in \mathcal{C}_2$ do
- 9: R'_2 considers *w* received.

Bijective Sending with Certificates: Example

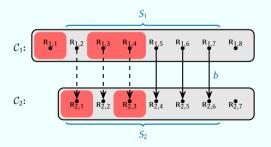
$$C_{1}: \begin{bmatrix} \mathbf{R}_{1,1} & \mathbf{R}_{1,2} & \mathbf{R}_{1,3} & \mathbf{R}_{1,4} & \mathbf{R}_{1,5} & \mathbf{R}_{1,6} & \mathbf{R}_{1,7} & \mathbf{R}_{1,8} \\ \end{bmatrix}$$

$$C_{2}: \begin{bmatrix} \mathbf{R}_{2,1}^{\bullet} & \mathbf{R}_{2,2}^{\bullet} & \mathbf{R}_{2,3}^{\bullet} & \mathbf{R}_{2,4}^{\bullet} & \mathbf{R}_{2,5}^{\bullet} & \mathbf{R}_{2,6}^{\bullet} & \mathbf{R}_{2,7}^{\bullet} \end{bmatrix}$$

Bijective Sending with Certificates: Example



Bijective Sending with Certificates: Example



Bijective Sending with Claims

Assume $2\mathbf{f}_{\mathcal{C}_1} + \mathbf{f}_{\mathcal{C}_2} + 1 \leq \min(\mathbf{n}_{\mathcal{C}_1}, \mathbf{n}_{\mathcal{C}_2}).$

We have $\tau_1 = \tau_2 = 2\mathbf{f}_{C_1} + \mathbf{f}_{C_2} + 1$.

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Bijective Sending with Claims

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Protocol for the sending cluster C_1 :

1:

Protocol for the receiving cluster \mathcal{C}_2 :

- 6: event $R_2 \in \mathcal{G}_{\mathcal{C}_2}$ receives $(w, cert(w, R'_1))$ from $R'_1 \in \mathcal{C}_1$ do
- 7: Broadcast $(w, cert(w, R'_1))$ to all replicas in C_2 .
- 8: event $R'_2 \in \mathcal{G}_{\mathcal{C}_2}$ receives $f_{\mathcal{C}_1} + 1$ messages $(w, cert(w, R'_1))$:
 - (i) each message is sent by a replica in \mathcal{C}_2 ;
 - (ii) each message carries the same value *w*; and
 - (iii) each message has a distinct signature $cert(w, R'_1), R'_1 \in C_1$

do

9: R'_2 considers *w* received.

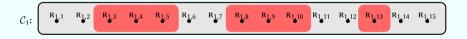
Consider bijective sending from C_1 to C_2 , $\mathbf{n}_{C_1} \ge \sigma_1 > \mathbf{n}_{C_2}$, with certificates.

- ▶ Bijective sending requires $f_{C_1} + f_{C_2} + 1$ distinct replicas in both clusters.
- Restrictive: clusters of roughly the same size.

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Generalize bijective sending



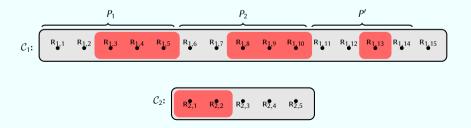
$$C_2: \begin{bmatrix} R_{2,1}^{\bullet} & R_{2,2}^{\bullet} \\ R_{2,3}^{\bullet} & R_{2,4}^{\bullet} & R_{2,5}^{\bullet} \end{bmatrix}$$

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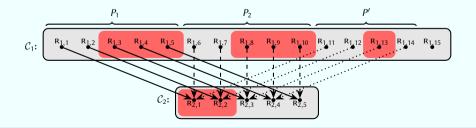


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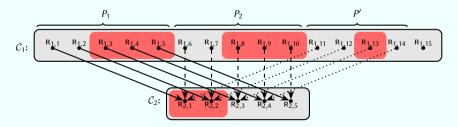


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- Partition σ_1 replicas of C_1 into \mathbf{n}_{C_2} -sized clusters.
- Bijective send from each cluster in the partition to C_2 .
- $\mathbf{n}_{C_1} \ge \sigma_1$ holds always if $\mathbf{n}_{C_1} > 3\mathbf{f}_{C_1}$ and $\mathbf{n}_{C_2} > 3\mathbf{f}_{C_2}$.



Partitioned Bijective Sending

Corollary

Consider the cluster-sending problem in which C_1 sends a value v to C_2 .

- 1. If $\mathbf{n}_{\mathcal{C}} > 3\mathbf{f}_{\mathcal{C}}$ for all clusters \mathcal{C} and replicas only have crash failures or omit failures, then (partitioned) bijective sending solves cluster-sending with optimal message complexity.
- 2. If $\mathbf{n}_{\mathcal{C}} > 3\mathbf{f}_{\mathcal{C}}$ for all clusters \mathcal{C} and clusters can produce certificates, then (partitioned) bijective sending solves cluster-sending with optimal message complexity.
- 3. If $\mathbf{n}_{\mathcal{C}} > 4\mathbf{f}_{\mathcal{C}}$ for all clusters \mathcal{C} and replicas can digitally sign claims, then (partitioned) bijective sending solves cluster-sending with optimal message complexity.

These protocols solve cluster-sending using $\mathcal{O}(\max(\mathbf{n}_{\mathcal{C}_1}, \mathbf{n}_{\mathcal{C}_2}))$ messages of size $\mathcal{O}(\|v\|)$ each.

Cluster-sending: Can we do Better?

Pessimistic

No: these algorithms are worst-case optimal.

Cannot do better than *linear communication* in the size of the clusters.

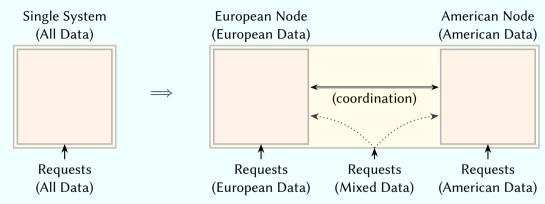
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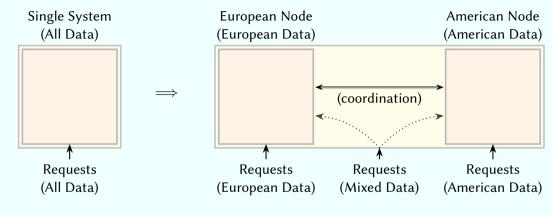
Probabilistic

Yes: if we randomly choose sender and receiver, then we often do much better! Probabilistic approach: expected-case only *constant communication* (four steps).

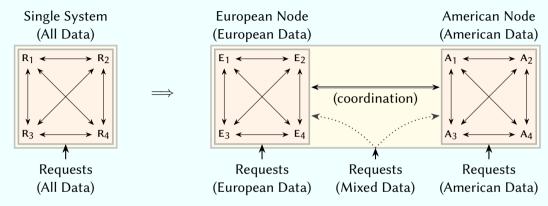


Partition the system: More storage and *potentially* more performance. Potentially *lower latencies* if data ends up closer to users.

Adding shards \implies adding throughput (parallel processing), adding storage.

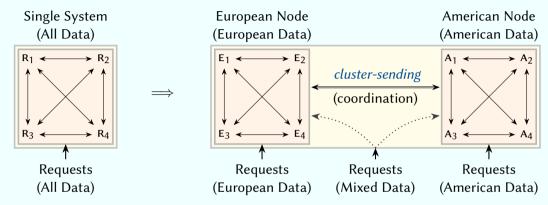


Resilient system



Resilient system

Individual shards are consensus-operated *blockchains*.



Resilient system

- ▶ Individual shards are consensus-operated *blockchains*.
- Communication between shards via *cluster-sending*.

A user interaction with a DBMS: transaction.

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- ► a single query;
- ▶ a set of queries;
- a interactive dialog between DBMS and program;

Contract between a DBMS and its users.

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- Given a *transaction* τ , a DBMS maintains
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- **Consistency** Execution of τ in *isolation* preserves data consistency.

E.g., integrety constraints-this is stronger than CAP-Consistency.

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Non-sharded resilient systems

- Consensus solves all of the above.
- ► In particular *replication order* is *execution order*.
- Consecutive execution guarantees ACID.

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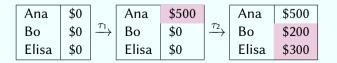
Ana	\$0		Ana	\$500
Во	\$0	$\xrightarrow{\tau_1}$	Во	\$0
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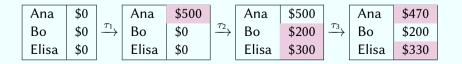
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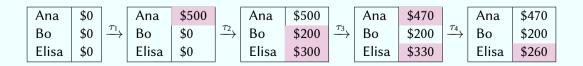


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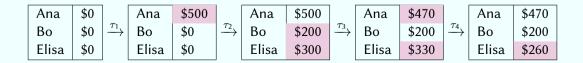
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 τ_4 = "remove \$70 from *Elisa*";

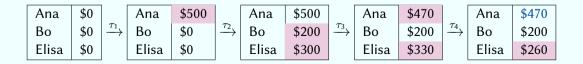
 $\tau_5 =$ "move \$500 from *Ana* to *Bo*".



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- τ_4 = "remove \$70 from *Elisa*";

 $\tau_5 = aborted$ (would invalidate balances).



Consider a transaction τ requested by client c in a resilient system.

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au must be *replicated* among all replicas of all shards affected by au!

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What is a consistent execution order *across* shards? Does it relate to the *replication order*?

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Dependencies on data in other shards? Writes to data in other shards?

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A single consensus does no longer solve all of the above!

Sharded system: Data is distributed over all shards.

A sharded banking system

Say we have 26 shards: C_a, C_b, \ldots, C_z ,

such that shard C_{ξ} holds accounts of people whose name starts with ξ .

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- shards $(\tau_1) = \{C_a\};$ isa", shards $(\tau_2) = \{C_b, C_e\};$ shards $(\tau_3) = \{C_a, C_e\};$ shards $(\tau_4) = \{C_e\}.$

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shards
$$(\tau_1) = \{C_a\}$$
; (single-shard)
shards $(\tau_2) = \{C_b, C_e\}$; (multi-shard)
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shards $(\tau_4) = \{C_e\}$. (single-shard)

Consider a banking example in which

Bo wants to transfer \$400 to Ana if Ana has at-least \$100 and Bo has at-least \$700,

Ana wants to transfer \$300 to Elisa if Ana has at-least \$500,

and no account is allowed to have a negative balance.

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 $au_2 = A \ge 500?, A := A - 300, E := E + 300.$

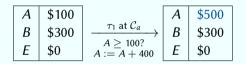
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A	\$100
В	\$300
Ε	\$0

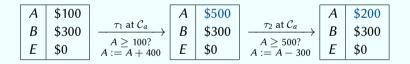
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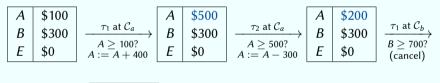
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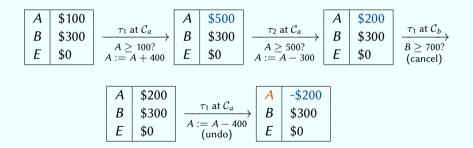
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A	\$200
B	\$300
E	\$0

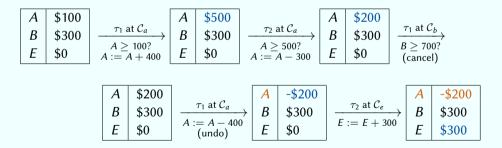
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An Example of Concurrent Execution-Revisited

Consider a banking example in which

Bo wants to transfer \$400 to Ana

if Ana has at-least \$100 and Bo has at-least \$700,

Ana wants to transfer \$300 to Elisa

if Ana has at-least \$500,

and no account is allowed to have a negative balance.

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Guarantee by an ACID-compliant system No account will ever have a negative balance.

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Consider the transaction τ :

au = "if *Ana* has \$500 and *Bo* has \$200, then move \$400 from *Ana* to *Elisa*; move \$100 from *Bo* to *Elisa*".

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What are the operations of τ ?

Depending on *how* the system executes τ and the database state:

- ▶ Might read from *Ana*'s account.
- ► Might read from *Bo*'s account.
- Might write to Ana's account.
- Might write to *Bo*'s account.
- ► Might write to *Elisa*'s account.

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Simplifying assumption

Each transaction is a sequence of read and write operations ending in *commit* or *abort*.

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Each transaction is a sequence of read and write operations ending in *commit* or *abort*. Read_{τ}(*Ana*), Read_{τ}(*Bo*), Write_{τ}(*Ana*), Write_{τ}(*Bo*), Read_{τ}(*Elisa*), Write_{τ}(*Elisa*), Commit_{τ}.

Consider again the transactions

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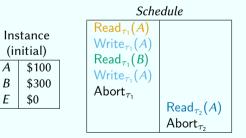
Serial schedule: τ_1 , then τ_2 (insufficient funds)

Instance (initial) A \$100 B \$300 E \$0

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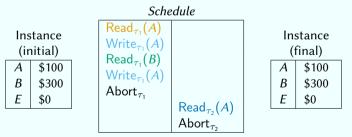
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Serial schedule: τ_1 , then τ_2 (Bob has sufficient funds)

 Instance

 (initial)

 A
 \$100

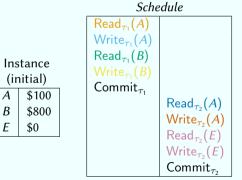
 B
 \$800

 E
 \$0

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Consider again the transactions

Α

В

F

 $\tau_1 = A > 100?, A := A + 400, B > 700?, B := B - 400;$ $\tau_2 = A > 500$?, A := A - 300, E := E + 300.

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Serial schedule: τ_2 , then τ_1 (Bob has sufficient funds)

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 (initial)

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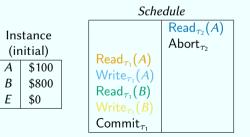
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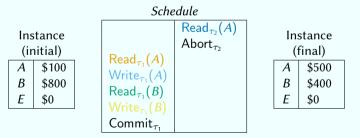
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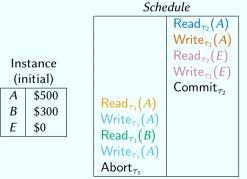
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Schedule $\operatorname{Read}_{\tau_2}(A)$ $Write_{\tau_2}(A)$ $\operatorname{Read}_{\tau_2}(E)$ Instance Instance $Write_{\tau_2}(E)$ (initial) (final) $Commit_{\tau_n}$ Α \$500 Α \$200 $\operatorname{Read}_{\tau_1}(A)$ В \$300 В \$300 $Write_{\tau_1}(A)$ F F \$300 \$0 $\operatorname{Read}_{\tau_1}(B)$ $Write_{\tau_1}(A)$ Abort $_{\tau_1}$

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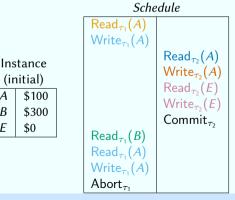
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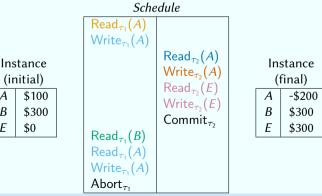
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Non-serial schedule-Another example

 Instance

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 \$500

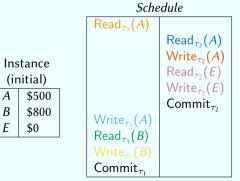
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Non-serial schedule-A third example

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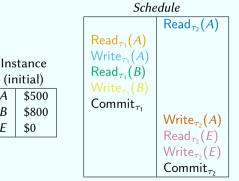
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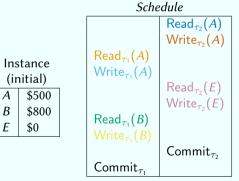
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Key observation: Serial schedules

Individual transactions make sense (do not violate consistency):

- No balance will ever get negative.
- No money disappears or appears out of thin air.

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As all data is shared: should the entire transaction be a single critical section? What if each transaction *locks the system*, executes, *releases the system*? This will enforce a *serial schedule* and eliminate any concurrency.

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Using fine-grained locks

A transaction τ that wants to access database object O will:

- waits until it obtains a lock on $O(Lock_{\tau}(O))$,
- then perform its operations on O (e.g., Read_{τ}(O) and Write_{τ}(O)), and

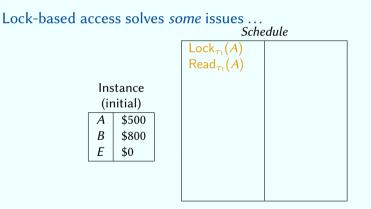
• finally release the lock on O (Release_{τ}(O)).

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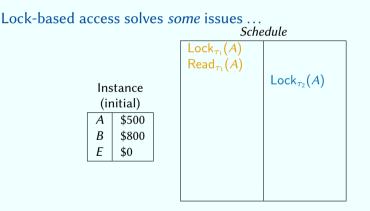
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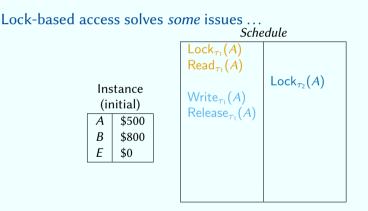
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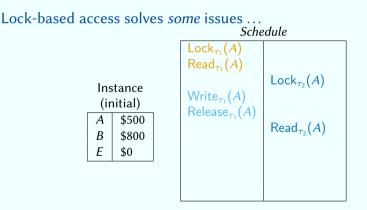
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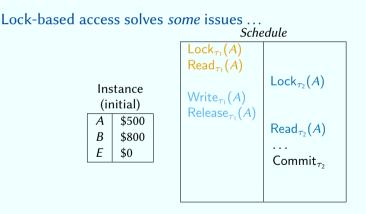
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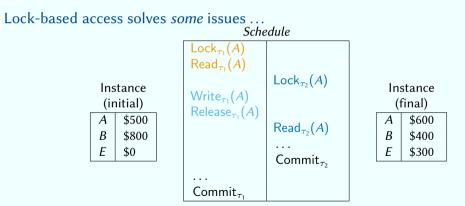


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Instance

(initial)

\$0

Α

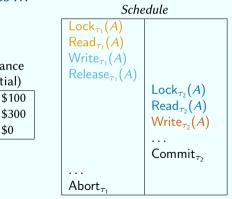
B

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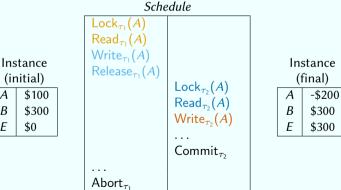
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Consider two transactions that both want to access Ana and Bo:

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$Lock_{\tau_1}(A)$ $Lock_{\tau_1}(B)$	$Lock_{ au_2}(B)$
$EOCN_{\tau_1}(D)$	$Lock_{ au_2}(A)$

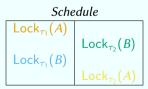
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Both transactions will wait forever: a deadlock!

Achieving Serializability with Locks

Locking itself does not guarantee *serializability*.

Some *locking protocols* (sets of rules on when to use locks) that do guarantee *serializability*.

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Execution of transaction τ adheres to 2PL if the execution is performed in two phases: Growing phase during which execution can obtains locks, and *not* release them; and Shrinking phase during which execution can release locks, and *not* obtain them, and any database object *O* is only operated on while holding lock Lock_{τ}(*O*).

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Notice–Nothing to deal with *deadlocks*.

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Assumption: Both transactions will succeed (Alice and Bob have sufficient funds)

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These are all *strict* 2PL: locks are released after the transactions commit.

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Two-Phase Locking and Deadlocks

Consider the transactions

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These transactions are strict 2PL.

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Some schedules will cause a deadlock

Schedule		
$Lock_{\tau_1}(A)$		
	$Lock_{ au_2}(B)$	
$Lock_{\tau_1}(B)$		
	$Lock_{ au_2}(A)$	

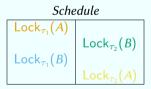
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Deadlocks are one of the issues arising from lock contention.

Pessimistic: make sure deadlocks cannot happen

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Example

Consider the transaction

 $\tau =$ "if *Bo* has \$500, then move \$200 from *Bo* to *Ana*".

Any schedule for τ needs to start with:

 $Lock_{\tau}(Ana), Lock_{\tau}(Bo), \ldots,$

we even lock Ana if Bo does not have funds.

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If a transaction tries to obtain a lock that is already held: *abort the transaction entirely*.

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▶ Will perform badly when there is a high amount of lock-contention.

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Result

- Many transactions can read at the same time.
- Read-write, write-read, and write-write conflicts are prevented.

The Cost of Serializability

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To improve performance, you can give up on serializability!

Level	Dirty Reads	Unrepeatable Read	Phantoms
READ UNCOMMITTED	Possible	Possible	Possible
READ COMMITTED	Not Possible	Possible	Possible
REPEATABLE READ	Not Possible	Not Possible	Possible
SERIALIZABLE	Not Possible	Not Possible	Not Possible

¹There are excellent papers on this topic! E.g., https://doi.org/10.1145/568271.223785 and https://doi.org/10.1016/0950-5849(96)01109-3 are recommended.

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Locking protocol for **READ UNCOMMITTED**

no read locks,

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Locking protocol for **READ COMMITTED**

- short-duration read (and predicate) locks before reading data, and
- long-duration write (and predicate) locks before writing data.

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Locking protocol for **REPEATABLE READ**

- short-duration predicate locks and long-duration read locks before reading data, and
- long-duration write (and predicate) locks before writing data.

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Locking protocol for SERIALIZABLE

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Locking protocol for **SERIALIZABLE** (2PL)

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- always withdraw money;
- only deposit money after either *commit* or *abort* is decided.

These executions guarantee that no account will have a negative balance!

Ingredients of Sharding in a Resilient Environment Multi-shard transaction execution of τ requires Replication of τ among shards. E.g., a two-phase commit step. Concurrency control to guarantee consistent execution of τ . E.g., using *locks* to prevent concurrent access to accounts.

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Fault-tolerant shards Each shard is a cluster of replicas that can be faulty.

Consensus for each *computation* within shards. Cluster-sending for any *communication* between shards.

Consensus is costly: Minimize its use.

The Orchestrate-Execute Model for Multi-Shard Transactions

Consider a multi-shard transaction τ :

- Processing is broken down into three types of *shard-steps*: vote, commit, and abort.
- Each shard-step is performed via one consensus step.
- ► Transfer control between steps using *cluster-sending*.

Execution method determines the local operations of a shard-step: locks, checking conditions, updating state,

Orchestration method determines how *control is transferred* between shard-steps: perform *votes*, collect *votes*, decide *commit* or *abort* τ .

Shard accounts by first letter of name

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Shard accounts by first letter of name

 $\tau =$ "if *Ana* has \$500 and *Bo* has \$200, then move \$400 from *Ana* to *Bo*."

 $\sigma_1 = \text{``Lock}_{\tau}(Ana)$; if *Ana* has \$500, then forward σ_2 to C_b (commit vote) else Release_{τ}(*Ana*) (abort vote)."

vote-step

 σ_1 at \mathcal{C}_a

Shard accounts by first letter of name

 $\tau =$ "if *Ana* has \$500 and *Bo* has \$200, then move \$400 from *Ana* to *Bo*."

 $\sigma_2 = \text{``Lock}_{\tau}(Bo)$; if *Bo* has \$200, then add \$400 to *Bo*; Release_{\tau}(Bo); and forward σ_3 to C_a (commit)

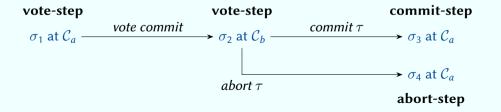
else Release_{τ}(*Bo*) and forward σ_4 to C_a (abort)."

vote-step vote-step $\sigma_1 \text{ at } \mathcal{C}_a \xrightarrow{} vote \ commit \xrightarrow{} \sigma_2 \text{ at } \mathcal{C}_b$

Shard accounts by first letter of name

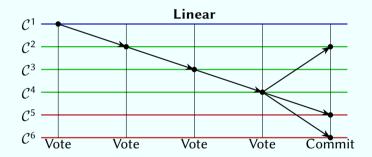
 $\tau =$ "if *Ana* has \$500 and *Bo* has \$200, then move \$400 from *Ana* to *Bo*."

 σ_3 = "remove \$400 from *Ana* and Release_{τ}(*Ana*)." σ_4 = "Release_{τ}(*Ana*)."



Resilient Orchestration Methods

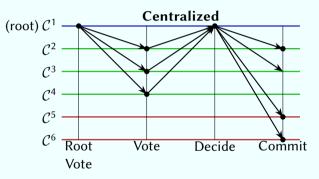
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Vote-steps in *sequence*, decide *centralized*, commit or abort in *parallel*.

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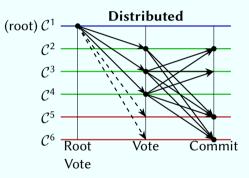
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Orchestration \approx two-phase commit, except that *shards never fail*.



Vote-steps in *parallel*, decide *decentralized*, commit or abort in *parallel*.

Resilient Execution Methods

Execution updates state and performs *concurrency control*.

- Write uncommitted execution for *free*: Due to consensus, shard-steps are performed in sequence on that shard.
- Higher isolation levels via two-phase locking:
 - read uncommitted execution: only write locks;
 - read committed execution: read locks during steps;
 - serializable execution: read and write locks.

Blocking locks (with linear orchestration) versus non-blocking locks.

